

A Timeline of Lattice Embeddings into the Turing Degrees

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Motivation

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“The attempt to determine the largest natural decidable fragment of the elementary theory of a given degree structure [...] produces a separation of the uniform fragment of the elementary theory from the pathological fragment”.

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Theorem (Lac68)

The elementary theory of (\mathcal{D}, \leq_T) is undecidable.

In this talk, we are interested in exploring decidability results about the \exists -theory of (\mathcal{D}, \leq_T) , $(\mathcal{D}, \leq_T, \vee, ')$, and $(\mathcal{D}, \leq_T, \vee, 0, ')$.

A classical example

Theorem (KP54)

Given any finite collection of noncomputable c.e. sets $\langle A_i \rangle_m$, for every $n \geq 1$ a collection of noncomputable c.e. sets $\langle B_i \rangle_n$ can be found such that:

- 1 $B_k \leq_T (\bigoplus_{i=1}^m A_i)'$ for every $1 \leq k \leq n$.
- 2 $B_k \not\leq_T A_i$ for every $1 \leq i \leq m$
- 3 $B_k \not\leq_T B_j$ for every $1 \leq j \leq n$ different than k .
- 4 For each k , $A_k \not\leq_T B_i$ for every $1 \leq i \leq n$.

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In the proof, the first condition is satisfied vacuously by using $(\bigoplus_{i=1}^n A_i)'$ as an oracle.

Definition (Requirements)

With index $i, j, k \leq s$ for every stage s , our requirements are as follows:

- R_e : For every $1 \leq i \leq m$, $\exists x[\phi_e^{A_i}(x) \downarrow \implies \phi_e^{A_i}(x) \neq \chi_{B_k}(x)]$.
- S_e : For every $1 \leq j \leq n$ different than k ,
 $\exists x[\phi_e^{B_j}(x) \downarrow \implies \phi_e^{B_j}(x) \neq \chi_{B_k}(x)]$.
- T_e : For every $1 \leq i \leq n$, $\exists x[\phi_e^{B_i}(x) \downarrow \implies \phi_e^{B_i}(x) \neq \chi_{A_k}(x)]$.

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Prior to the initialization of any strategy, B_k is defined as the empty set for every $1 \leq k \leq n$. It can also be assumed that witnesses come from an increasing monotonic sequence of natural numbers.

Strategy for R_e : For every $1 \leq i \leq m$ and $1 \leq k \leq n$.

- 1 Choose a new unique witness $x \in \mathbb{N}$ and use our oracle to check if $\phi_e^{A_i}(x)$ halts.
- 2 If $\phi_e^{A_i}(x) \downarrow = 0$, enumerate x into B_k .

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Strategy for S_k : For every $1 \leq j \leq n$ different than k and $1 \leq k \leq n$.

- 1 Choose a new unique witness $x \in \mathbb{N}$ and wait for $\phi_e^{B_j}(x)$ to halt.
- 2 If $\phi_e^{B_j}(x) \downarrow = 0$ with use u , enumerate x into B_k and put a restraint on $B_j \upharpoonright_u$.

Strategy for T_k : For every $1 \leq i \leq m$ and $1 \leq k \leq n$.

- 1 Choose a new unique witness $x \in A_i$ and wait for $\phi_e^{B_k}(x)$ to halt.
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Injuries: Both R_e and S_k strategies might cause injuries to lower priority strategies when enumerating elements into B_k . When this happens, the injured strategies chooses a new witness and restart.

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We may define a *rank* for each element of our finite upper semilattice. Each $x \in L$ with no $y \in L$ such that $y \leq_L x$ will have rank 0 and so on. As the lattice is finite, then there will only be finitely many ranks and finitely many elements of any given rank.

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As a direct result, we can obtain that the \exists -theory of (\mathcal{D}, \leq_T) is decidable.

Definition

A jump upper semilattice is a structure $\mathcal{J} = \langle J, \leq, \vee, j \rangle$ such that:

- $\langle J, \leq \rangle$ is a partial ordering;
- For all $x, y \in J$, $x \vee y$ is the least upper bound of x and y ;
- $j(\cdot)$ is a unary jump operator i.e. for all $x, y \in J$, $x < j(x)$; and if $x \leq y$, then $j(x) \leq j(y)$.

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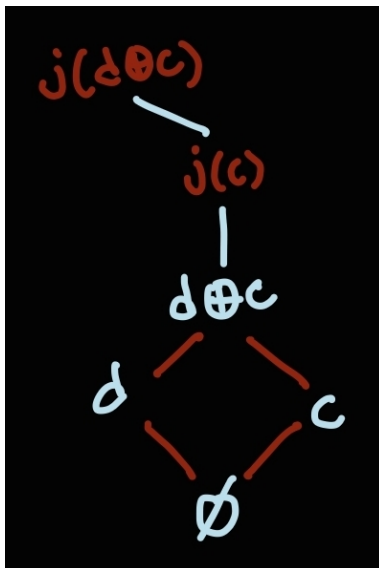
As a direct result, we have that the \exists -theory of $(\mathcal{D}, \leq_T, \vee, ')$ is decidable.

$(\mathcal{D}, \leq_T, \vee, 0, ')$

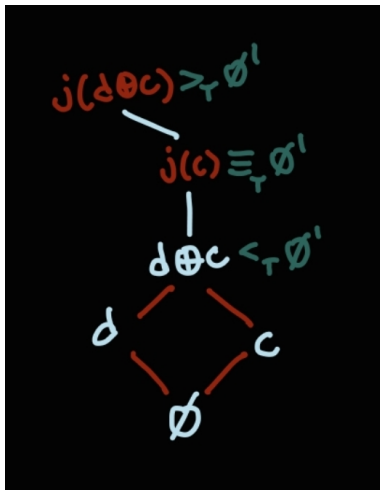
Theorem (L06)

The \exists -theories of $(\mathcal{D}, \leq_T, \vee, 0, ')$ and $(\mathcal{D}_{\text{REA}}, \leq_T, \vee, 1, ')$ are decidable.

Science fiction: Low Embeddings



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Definition (Global 1-true stages)

A global 1-true stage ordering is a computable partial ordering \preceq on $\mathbb{N}^{<\mathbb{N}}$ that satisfies the following properties:

- 1 $\langle \rangle \preceq \tau$ for all τ ;
- 2 If $\sigma \preceq \tau$, then $\sigma \subseteq \tau$;
- 3 For each $X \in \mathbb{N}^{\mathbb{N}}$, there is an infinite sequence of initial segments of X such that $\tau_0 \preceq \tau_1 \preceq \dots \subset X$; and
- 4 For every $\tau \subset \sigma \subset \rho$, if $\tau \preceq \rho$, then $\tau \preceq \sigma$.

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- 4 For every $\tau \subset \sigma \subset \rho$, if $\tau \preceq \rho$, then $\tau \preceq \sigma$.

When $\sigma \preceq \tau$, we say that τ believes σ . For substrings defined as in property (3), we say that τ is X -true and write $\tau \preceq X$.

Definition

We say that \mathcal{A} is complete if, for every $X \in \mathbb{N}^{\mathbb{N}}$ we have that $\mathcal{T}_X := \langle \tau \in \mathbb{N}^{\langle \mathbb{N} \rangle} : \tau \mathcal{A} X \rangle \equiv_{\mathcal{T}} X'$ uniformly in X .

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Following Lachlan's notion of *true stages*, our constructions will use \mathcal{T}_\emptyset as their \emptyset' -oracle. As we cannot directly access \mathcal{T}_\emptyset , we will define a series of stages \mathcal{T}_σ that approximate it in a computable way.

Definition (σ Stages)

Consider an approximation of \emptyset' via finite binary sequences

$\sigma_s = \langle \sigma_{i \leq s, s} \rangle \in \mathbb{N}^{<\mathbb{N}}$ defined as follows:

① $\sigma_{0,0} = 0$, and

② $\sigma_{i,s} = \begin{cases} 1 & \phi_i(i) \downarrow \text{ in } s \text{ steps} \\ 0 & \text{Otherwise} \end{cases}$.

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Definition

We say that our construction \mathcal{T}_{σ_j} -believes \mathcal{T}_{σ_k} when $\mathcal{T}_{\sigma_k} \subseteq \mathcal{T}_{\sigma_j}$ and $\tau \preceq \sigma_j$ for every $\tau \preceq \sigma_k$.

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Definition (σ -injuries)

Let $k < s$ and $|\mathcal{T}_{\sigma_k}| = l$. At stage s , if it is found that $\mathcal{T}_{\sigma_k} \neq \mathcal{T}_{\sigma_s} \upharpoonright l$ we say that every strategy that has used oracle \mathcal{T}_{σ_k} *in order to carry out an action* has been σ -injured and require attention.

Some considerations

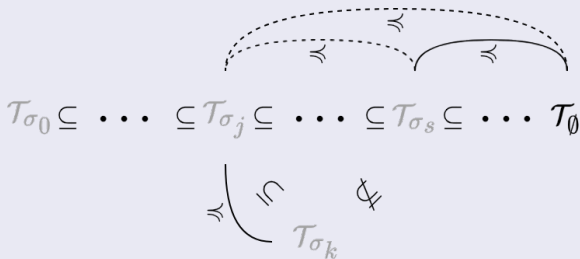
As long as our constructions are able to successfully recover from σ -injuries, they will be able to properly carry out their work over the infinite path of \emptyset -true stages. In order to achieve this, they will follow these rules:

- 1 They will always act with the current \mathcal{T}_σ as an oracle;
- 2 At the beginning of every stage, the current \mathcal{T}_σ will be used to revisit, in order of priority, all previously initiated strategies in order to identify possible σ -injuries. In other words, they will update their set of \mathcal{T}_σ -beliefs at the beginning of every stage; and
- 3 σ -injuries will take priority over regular injuries that arise from the interaction between strategies.

Lemma

Let the relations between \mathcal{T}_{σ_0} , \mathcal{T}_{σ_j} , \mathcal{T}_{σ_k} , \mathcal{T}_{σ_s} , and \mathcal{T}_\emptyset hold as expressed in figure 1. Then, the following two statements hold:

- If our construction \mathcal{T}_\emptyset -believes \mathcal{T}_{σ_s} and \mathcal{T}_{σ_s} -believes \mathcal{T}_{σ_j} , then it \mathcal{T}_\emptyset -believes \mathcal{T}_{σ_j} ; and
- If our construction \mathcal{T}_\emptyset -believes \mathcal{T}_{σ_s} but does not \mathcal{T}_{σ_s} -believe \mathcal{T}_{σ_k} , then it does not \mathcal{T}_\emptyset -believe \mathcal{T}_{σ_k} either.



A toy example

With index i in \mathbb{N} , these are our requirements:

- L_i : \mathbf{c} is low;
- N_i : \mathbf{d} is not low; and
- \dots .

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- N_i : \mathbf{d} is not low; and
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What will we do?

Use \mathcal{T}_σ to ensure L_i and N_i always hold.

L_i strategies

At first, \mathbf{c} is set to be the empty set.

- 1 Upon initialization at stage $s > 1$, \mathcal{T}_σ is used to check if $\Phi_s^{\mathbf{c}[s]}(s)$ halts. If so, a restrain is put on \mathbf{c} with the use of that computation, u_s .
- 2 If revisited at stage k , \mathcal{T}_σ is used to check if $\Phi_s^{\mathbf{c}[k]}(s)$ halts. If so, a restrain is put on \mathbf{c} with the use of that computation, u_k .

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Injuries

- 1 If there is a low enumeration, say between u_m and u_n , all L_i strategies with $i > m$ are restarted in order of priority.
- 2 If it is discovered that a restrain was placed based on incorrect information from a past \mathcal{T}_σ , all L_i strategies with $i \geq k$ are restarted in order of priority.

Some Questions.

- ① Is this weaker than Lerman's framework?
- ② Can you "bruteforce" the emeddings of finite JUSL with finite support?
- ③ Are there any nontrivial examples where this "bruteforcing" makes sense?

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Thank you!

