

A FIXED POINT THEOREM OF KRASNOSELSKII-SCHAEFER TYPE

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Abstract. In this paper we focus on three fixed point theorems and an integral equation. Schaefer's fixed point theorem will yield a T -periodic solution of

$$(1) \quad x(t) = a(t) + \int_{t-h}^t D(t, s)g(s, x(s)) ds$$

if D and g satisfy certain sign conditions independent of their magnitude. A combination of the contraction mapping theorem and Schauder's theorem (known as Krasnoselskii's theorem) will yield a T -periodic solution of

$$(2) \quad x(t) = f(t, x(t)) + \int_{t-h}^t D(t, s)g(s, x(s)) ds$$

if f defines a contraction and if D and g are small enough.

We prove a fixed point theorem which is a combination of the contraction mapping theorem and Schaefer's theorem which yields a T -periodic solution of (2) when f defines a contraction mapping, while D and g satisfy the aforementioned sign conditions.

1. Introduction. We are interested in proving that equations of the type

$$(1) \quad x(t) = f(t, x(t)) - \int_{t-h}^t D(t, s)g(s, x(s)) ds$$

possess a T -periodic solution when D is essentially a positive kernel and f is a contraction. In particular, D may be large.

Equations of this form are interesting in their own right. It is an equation with memory: the present value of x depends on its past history.

But (1) can also arise from a much more familiar problem such as

$$(D) \quad x'(t) = -a(t)x(t) - g(t, x(t))$$

where $a(t+T) = a(t)$ and $g(t+T, x) = g(t, x)$ for some $T > 0$. Krasnoselskii (cf. Schauder [14] and Smart [15; p. 31]) observed that in a variety of problems the inversion of a perturbed differential operator yields a contraction and a compact map. For

example, in (D) we write

$$\left(x \exp \int_0^t a(s) ds \right)' = -g(t, x) \exp \int_0^t a(s) ds$$

and integrate from $t - T$ to t obtaining

$$(ID) \quad x(t) = x(t - T) \exp - \int_{t-T}^t a(s) ds \\ - \int_{t-T}^t g(u, x(u)) \left[\exp - \int_u^t a(s) ds \right] du.$$

If $\exp - \int_{t-T}^t a(s) ds = Q < 1$ and if $(\mathcal{B}, \|\cdot\|)$ is the Banach space of continuous T -periodic functions $\varphi : R \rightarrow R$, then (ID) can be expressed as

$$(ID) \quad \varphi(t) = (B\varphi)(t) + (A\varphi)(t)$$

where B is a contraction and A maps bounded subsets of \mathcal{B} into compact subsets of \mathcal{B} . In fact, B can take a portion of the integral which might not be well-behaved in some sense. The above integral maps bounded sets of T -periodic functions into equicontinuous sets, as may be seen in the last section in the proof of Lemma 2.

Contraction mappings shrink sets. Krasnoselskii showed that if $B\varphi + A\psi$ shrinks a certain set, then there will be a fixed point, a solution of (ID), which is in \mathcal{B} and, hence, is periodic. His result can be stated as follows (Krasnoselskii [8; p. 370] or Smart [15; p. 31]). Concerning the terminology of compact mapping used in this theorem, Krasnoselskii is using the convention of Smart [15;p. 25] to mean the following: Let A map a set M into a topological space X . If AM is contained in a compact subset of X , we say that A is compact. In particular, M need not be bounded.

Theorem K. *Let M be a closed convex nonempty subset of a Banach space $(\mathcal{B}, \|\cdot\|)$. Suppose that A and B map M into \mathcal{B} such that*

- (i) $x, y \in M \Rightarrow Ax + By \in M$,
- (ii) A is compact and continuous,
- (iii) B is a contraction mapping.

Then $\exists y \in M$ with $y = Ay + By$.

As we will emphasize again soon, the assumptions of the theorem are verified *directly from the functions appearing* in the operator equation (ID) and the proof rests on Schauder's second fixed point theorem.

There is a theorem of Schaefer ([13] or Smart [15; [p. 29]) which competes with Schauder's and which usually yields much more, but it also requires much more. Schaefer's theorem requires that we have an a priori bound on *utterly unknown solutions* of an operator equation $\varphi = \lambda A\varphi$ for $0 < \lambda < 1$, in contrast with Schauder's which requires conditions on the *clearly visible* mapping A . Schaefer's theorem may be stated as follows. This is Smart's formulation; Schaefer proved the result for a locally convex space.

Theorem S. *Let $(\mathcal{B}, \|\cdot\|)$ be a normed space, H a continuous mapping of \mathcal{B} into \mathcal{B} which is compact on each bounded subset X of \mathcal{B} . Then either*

- (i) the equation $x = \lambda Hx$ has a solution for $\lambda = 1$, or*
- (ii) the set of all such solutions x , for $0 < \lambda < 1$, is unbounded.*

The problem which we focus on here is this: Can we substitute Schaefer-type conditions on A for Krasnoselskii's Schauder-type conditions? We show that we can and that there are interesting applications. In particular, for (1) Krasnoselskii would require f to be a contraction and Dg to be small, while we allow Dg to be large, provided D and g satisfy certain conditions.

2. A fixed point theorem. We start with an equation

$$x = Bx + Ax$$

where B is a contraction. Now contractions shrink functions, but we are led to the homotopy equation

$$x = \lambda B(x/\lambda) + \lambda Ax$$

and we still need $\lambda B(x/\lambda)$ to shrink functions. Our first result shows that it does; applications depend heavily on this.

Proposition. *If $(\mathcal{B}, \|\cdot\|)$ is a normed space, if $0 < \lambda < 1$, and if $B : \mathcal{B} \rightarrow \mathcal{B}$ is a contraction mapping with contraction constant α , then $\lambda B \frac{1}{\lambda} : \mathcal{B} \rightarrow \mathcal{B}$ is also a contraction mapping with contraction constant α , independent of λ ; in particular*

$$\|\lambda B(x/\lambda)\| \leq \alpha\|x\| + \|B0\|.$$

Proof.

To see that $\lambda B \frac{1}{\lambda}$ is a contraction, $x \in \mathcal{B} \Rightarrow x/\lambda \in \mathcal{B} \Rightarrow B(x/\lambda) \in \mathcal{B} \Rightarrow \lambda B(x/\lambda) \in \mathcal{B}$; moreover, $x, y \in \mathcal{B} \Rightarrow$

$$\begin{aligned} \|\lambda B(x/\lambda) - \lambda B(y/\lambda)\| &= \lambda \|B(x/\lambda) - B(y/\lambda)\| \\ &\leq \lambda \alpha \|(x/\lambda) - (y/\lambda)\| = \alpha \|x - y\|. \end{aligned}$$

To obtain the bound, for any $x \in \mathcal{B}$ we have

$$\begin{aligned} \|\lambda B(x/\lambda)\| &= \lambda \|B(x/\lambda)\| = \\ &\lambda (\|B(x/\lambda) - B0 + B0\|) \\ &\leq \lambda (\|B(x/\lambda) - B0\| + \|B0\|) \\ &\leq \lambda (\alpha \|(x/\lambda) - 0\| + \|B0\|) \\ &= (\lambda \alpha / \lambda) \|x\| + \|B0\|, \end{aligned}$$

as required.

Theorem 1. *Let $(\mathcal{B}, \|\cdot\|)$ be a Banach space, $A, B : \mathcal{B} \rightarrow \mathcal{B}$, B a contraction with contraction constant $\alpha < 1$, and A continuous with A mapping bounded sets into compact sets. Either*

- (i) $x = \lambda B(x/\lambda) + \lambda Ax$ has a solution in \mathcal{B} for $\lambda = 1$, or
- (ii) the set of all such solutions, $0 < \lambda < 1$, is unbounded.

Proof.

By the proposition, $\lambda B \frac{1}{\lambda}$ is a contraction mapping from \mathcal{B} into \mathcal{B} . Consequently, for each $y \in \mathcal{B}$, the mapping $x \rightarrow \lambda B(x/\lambda) + \lambda Ay$ is also a contraction with unique solution $x = \lambda B(x/\lambda) + \lambda Ay$ in \mathcal{B} . This yields

$$\frac{x}{\lambda} = B \frac{x}{\lambda} + Ay$$

or

$$(I - B)\frac{x}{\lambda} = Ay$$

so

$$\frac{x}{\lambda} = (I - B)^{-1}Ay$$

and

$$(*) \quad x = \lambda(I - B)^{-1}Ay.$$

Now $(I - B)^{-1}$ exists and is continuous (cf. Smart [15; p. 32]). Since A is continuous and maps bounded sets into compact sets, so does $(I - B)^{-1}A$ (The proof given by Kreyszig [9; p. 412, 656] is valid for general metric spaces.).

By Schaefer's theorem, either $(*)$ has a solution with $x = y$ for $\lambda = 1$ (hence, (i) has a solution for $\lambda = 1$), or the set of all such solutions, $0 < \lambda < 1$, is unbounded.

This completes the proof.

3. An example. Equation (1) is related to a large class of important problems going back at least to Volterra [16] who suggested that the growth of solutions of

$$x' = - \int_0^t k(t-s)g(x(s)) ds$$

could be controlled if $xg(x) > 0$ for $x \neq 0$, $k(t) > 0$, $k'(t) < 0$, $k''(t) > 0$. Appropriate details were provided by Levin [10] through construction of a very clever Liapunov function. Subsequently, both that equation and its integral equation counterpart were widely studied in the literature ([6], [7], [11], [12]) both by means of Liapunov functions and by transform theory.

We have studied integrodifferential equations in ([3], [4]) and variants of (1) in ([1], [2], [5]) when $f(t, x)$ is independent of x using Schaefer's theorem or an analog; but Schaefer's theorem does not apply here since $f(t, x)$ can not define a compact mapping. Thus, we are interested in Krasnoselskii's theorem. But we want the kernel to be free to grow large; this means that we will not be able to satisfy Krasnoselskii's conditions. That was the motivation for our theorem.

Let $(\mathcal{B}, \|\cdot\|)$ be the Banach space of continuous T -periodic functions $\varphi : R \rightarrow R$ with the supremum norm. Consider (1) and suppose there is a $T > 0$ and $\alpha \in (0, 1)$ with:

$$(2) \quad f(t+T, x) = f(t, x), \quad D(t+T, s+T) = D(t, s), \quad g(t+T, x) = g(t, x),$$

$$(3) \quad t-h \leq s \leq t \text{ implies that } D_s(t, t-h) \geq 0,$$

$$D_{st}(t, s) \leq 0, \quad D(t, t-h) = 0,$$

$$(4) \quad |f(t, x) - f(t, y)| \leq \alpha|x - y|, \quad xg(t, x) \geq 0,$$

$$(5) \quad \forall k > 0 \exists P > 0 \exists \beta > 0 \text{ with}$$

$$2\lambda[-(1-\alpha)xg(t, x) + k|g(t, x)|] \leq \lambda[P - \beta|g(t, x)|],$$

$$(6) \quad f, g, \text{ and } D_{st} \text{ are continuous.}$$

Theorem 2. *If (2)–(6) hold, then (1) has a T -periodic solution.*

Proof.

Define a mapping $B : \mathcal{B} \rightarrow \mathcal{B}$ by $\varphi \in \mathcal{B}$ implies

$$(7) \quad (B\varphi)(t) = f(t, \varphi(t)).$$

Lemma 1. *If B is defined by (7), then B is a contraction mapping from \mathcal{B} into \mathcal{B} with contraction constant α of (4).*

Proof.

If $\varphi, \psi \in \mathcal{B}$, then

$$\begin{aligned} \|B\varphi - B\psi\| &= \sup_{t \in [0, T]} |(B\varphi)(t) - (B\psi)(t)| \\ &= \sup_{t \in [0, T]} |f(t, \varphi(t)) - f(t, \psi(t))| \\ &\leq \sup_{t \in [0, T]} \alpha|\varphi(t) - \psi(t)| = \alpha\|\varphi - \psi\|, \end{aligned}$$

as required.

Define a mapping $A : \mathcal{B} \rightarrow \mathcal{B}$ by $\varphi \in \mathcal{B}$ implies

$$(8) \quad (A\varphi)(t) = - \int_{t-h}^t D(t, s)g(s, \varphi(s)) ds.$$

Lemma 2. *If A is defined by (8) then $A : \mathcal{B} \rightarrow \mathcal{B}$, A is continuous, A maps bounded sets into compact sets.*

Proof.

This is a standard exercise. For completeness, here are the details. Let $k > 0$ be given, $\varphi \in \mathcal{B}$ be an arbitrary element with $\|\varphi\| \leq k$. By the continuity of D , if $0 \leq t \leq T$ and $-h \leq s \leq T$, there is an $M > 0$ with

$$(I) \quad |D(t, s)| \leq M.$$

By the uniform continuity of D on $[0, T] \times [-h, T]$, for each $\varepsilon > 0$ there is a $\delta_1 > 0$ such that $u, v \in [0, T]$, $s, t \in [-h, T]$, $|u - v| + |s - t| \leq \delta_1$ implies

$$(II) \quad |D(u, s) - D(v, t)| \leq \varepsilon.$$

Next, since g is continuous on $[0, T] \times [-k, k]$ and periodic in t there is an $L > 0$ with

$$(III) \quad |g(s, x)| \leq L \text{ for } s \in \mathbb{R} \text{ and } x \in [-k, k].$$

In fact, by the uniform continuity of g on that set, for any $\varepsilon > 0$ there is a positive $\delta_2(\varepsilon) < T$ such that if $s, t \in [0, T]$ and $x, y \in [-k, k]$ with $|s - t| + |x - y| \leq \delta_2$, then $|g(s, x) - g(t, y)| \leq \varepsilon$ and, by the periodicity,

$$(IV) \quad |g(s, x) - g(t, y)| \leq \varepsilon \text{ for } s, t \in \mathbb{R} \text{ and } x, y \in [-k, k]$$

with $|s - t| + |x - y| < \delta_2$.

The assertions about A will now follow. If $\varphi \in \mathcal{B}$, a change of variable shows that $A\varphi$ is T -periodic. Clearly, if $\varphi \in \mathcal{B}$, then $A\varphi$ is continuous. Thus, $A\varphi \in \mathcal{B}$.

We now show that A maps bounded sets into compact sets. First,

$$(V) \quad \{A\varphi : \varphi \in \mathcal{B} \text{ and } \|\varphi\| \leq k\} \text{ is equicontinuous.}$$

To see this, note that if $u < v$, then

$$\begin{aligned} (A\varphi)(u) - (A\varphi)(v) &= - \int_{u-h}^{v-h} D(u, s)g(s, \varphi(s)) ds \\ &\quad - \int_{v-h}^u [D(u, s) - D(v, s)]g(s, \varphi(s)) ds \\ &\quad + \int_u^v D(v, s)g(s, \varphi(s)) ds. \end{aligned}$$

By (I)-(III), for all $u, v \in [0, T]$ with $|u - v| < \delta_1$, if $\varphi \in \mathcal{B}$ and $\|\varphi\| \leq k$, then

$$\begin{aligned} |(A\varphi)(u) - (A\varphi)(v)| &\leq ML|u - v| + L|u - v + h|\varepsilon \\ (VI) \quad &+ ML|u - v| \\ &\leq 2ML\delta_1 + L(\delta_1 + h)\varepsilon. \end{aligned}$$

Next, for $\varphi \in \mathcal{B}$ and $\|\varphi\| \leq k$, it follows from (I) and (III) that $|(A\varphi)(u)| \leq LMh$ so that

$$(VII) \quad \|A\varphi\| \leq LMh \text{ for } \varphi \in \mathcal{B} \text{ and } \|\varphi\| \leq k.$$

By Ascoli's theorem A maps bounded sets into compact sets.

To see that A is continuous, fix φ and $\psi \in \mathcal{B}$ with $\|\varphi - \psi\| < \delta_2$, $\|\varphi\| \leq k$, $\|\psi\| \leq k$. Then for $0 \leq u \leq T$ we have by (I) and (IV) that

$$\begin{aligned} |(A\varphi)(u) - (A\psi)(u)| &\leq \int_{u-h}^u |D(u, s)| |g(s, \varphi(s)) - g(s, \psi(s))| ds \\ &\leq Mh\varepsilon. \end{aligned}$$

This completes the proof of Lemma 2.

Next, notice that if $B : \mathcal{B} \rightarrow \mathcal{B}$ is defined by

$$(Bx)(t) = f(t, x(t)), \text{ then } \left(\lambda B \frac{x}{\lambda} \right)(t) = \lambda f\left(t, \frac{x(t)}{\lambda}\right).$$

Lemma 3. *There is a $K \geq 0$ such that if $0 < \lambda < 1$ and if $x \in \mathcal{B}$ solves*

$$(1_\lambda) \quad x(t) = \lambda f\left(t, \frac{x}{\lambda}\right) - \lambda \int_{t-h}^t D(t, s)g(s, x(s)) ds$$

then $\|x\| \leq K$.

Proof.

Let $x \in \mathcal{B}$ solve (1_λ) and define

$$V(t) = \lambda^2 \int_{t-h}^t D_s(t, s) \left(\int_s^t g(v, x(v)) dv \right)^2 ds.$$

This is a type of Liapunov function obtained from (1_λ) by squaring $x - \lambda f$, integrating by parts, and using the Schwarz inequality.

Now $D_{st}(t, s) \leq 0$ so

$$\begin{aligned} V'(t) &\leq -\lambda^2 D_s(t, t-h) \left(\int_{t-h}^t g(v, x(v)) dv \right)^2 \\ &\quad + 2\lambda^2 g(t, x) \int_{t-h}^t D_s(t, s) \int_s^t g(v, x(v)) dv ds. \end{aligned}$$

The first term on the right-hand-side is not positive by (3); if we integrate the last term by parts and use (3) again we have

$$\begin{aligned} V'(t) &\leq 2\lambda g(t, x) \int_{t-h}^t \lambda D(t, s) g(s, x(s)) ds \\ &= 2\lambda g(t, x) \left[\lambda f\left(t, \frac{x}{\lambda}\right) - x(t) \right] \end{aligned}$$

from (1_λ). But by the reasoning in the proposition,

$$\left| \lambda f\left(t, \frac{x}{\lambda}\right) \right| \leq \alpha |x(t)| + |f(t, 0)| \leq \alpha |x(t)| + k$$

for some $k > 0$. Thus,

$$\begin{aligned} V'(t) &\leq 2\lambda \{ |g(t, x)| [\alpha |x| + k] - xg(t, x) \} \\ &= 2\lambda [|\alpha xg(t, x)| + k|g(t, x)| - xg(t, x)] \\ &\leq 2\lambda [-(1 - \alpha)xg(t, x) + k|g(t, x)|]. \end{aligned}$$

As $\alpha < 1$, from (5) we have

$$V'(t) \leq \lambda [-\beta |g(t, x)| + P].$$

Thus, $x \in \mathcal{B}$ implies $V \in \mathcal{B}$ so that

$$0 = V(T) - V(0) \leq \lambda \left[-\beta \int_0^T |g(t, x(t))| dt + PT \right]$$

or

$$(9) \quad \int_0^T |g(t, x(t))| dt \leq PT/\beta$$

since $\lambda > 0$. As $g(t, x(t)) \in \mathcal{B}$, there is an $n > 0$ with

$$(10) \quad \int_{t-h}^t |g(t, x(t))| dt \leq n.$$

Taking $M = \max_{-h \leq s \leq t \leq T} |D(t, s)|$, then from the proposition, (1 λ), and (10) we have

$$\begin{aligned} |x(t)| &\leq \left| \lambda f\left(t, \frac{x}{\lambda}\right) \right| + \lambda \left| \int_{t-h}^t D(t, s) g(s, x(s)) ds \right| \\ &\leq \alpha |x(t)| + k + Mn \end{aligned}$$

or

$$\|x\| \leq (Mn + k)/(1 - \alpha),$$

as required. Application of Theorem 1 completes the proof.

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